

td ST4.0

No 43

$$\textcircled{1} \quad \vec{OG} = \frac{a}{3} \vec{x} + \frac{h}{3} \vec{z}$$

$$M = \rho_b \frac{h \cdot l}{2} \cdot l$$

$$M = 2600 \frac{30 \cdot 20}{2} 80$$

$$M = 62,4 \cdot 10^3 \text{ tonnes}$$

$$(10^6 \text{ kg})$$

$$\textcircled{2} \quad \left\{ T_{P \rightarrow b} \right\}_G = \left\{ \begin{array}{cc} 0 & 0 \\ 0 & 0 \\ -Mg & 0 \end{array} \right\}_{G,R}$$

Varignon:  $\vec{M}_{O, P \rightarrow b} = \vec{M}_{G, P \rightarrow b} + \vec{OG} \wedge \vec{R}_{P \rightarrow b}$

$$= \left( \frac{a}{3} \vec{x} + \frac{h}{3} \vec{z} \right) \wedge -Mg \vec{z}$$

$$\left\{ \begin{array}{l} \vec{x} \wedge \vec{z} = -\vec{y} \\ \vec{z} \wedge \vec{z} = \vec{0} \end{array} \right.$$

$$\vec{M}_{O, P \rightarrow b} = \frac{a}{3} Mg \vec{y}$$

d'où  $\left\{ T_{P \rightarrow b} \right\} = \left\{ \begin{array}{cc} 0 & 0 \\ 0 & \frac{a}{3} Mg \\ -Mg & 0 \end{array} \right\}_{O,R}$

$$\textcircled{3} \quad \left\{ T_{e \rightarrow b} \right\} = \left\{ \begin{array}{l} \vec{R}_{e \rightarrow b} = \int_0^h \lambda(z) \vec{x} dz \\ \vec{M}_{O, e \rightarrow b} = \int_0^h \vec{OQ} \wedge \lambda(z) \vec{x} dz \end{array} \right\}_O$$

$$\begin{aligned} \bullet \vec{R}_{e \rightarrow b} &= \int_0^h \rho_e g l (h-z) + \rho_0 l dz \vec{x} \\ &= \left[ \rho_e g l \left( hz - \frac{z^2}{2} \right) + \rho_0 l z \right]_0^h \vec{x} \\ &= \left( \rho_e g l \left( h^2 - \frac{h^2}{2} \right) + \rho_0 l h \right) \vec{x} \end{aligned}$$

$$\vec{R}_{e \rightarrow b} = \left( \rho_e g l \frac{h^2}{2} + \rho_0 l h \right) \vec{x}$$

$$\bullet \vec{M}_{O, e \rightarrow b} = \int_0^h z \vec{z} \wedge (\rho_e g l (h-z) + \rho_0 l) \vec{x} dz$$

avec  $\vec{z} \wedge \vec{x} = \vec{y}$

$$= \int_0^h \rho_e g l (hz - z^2) + \rho_0 l z dz \cdot \vec{y}$$

$$= \left[ \rho_e g l \left( h \frac{z^2}{2} - \frac{z^3}{3} \right) + \rho_0 l \frac{z^2}{2} \right]_0^h \vec{y}$$

$$= \left( \rho_e g l \left( \frac{h^3}{2} - \frac{h^3}{3} \right) + \rho_0 l \frac{h^2}{2} \right) \vec{y}$$

$$\vec{M}_{O, e \rightarrow b} = \left( \rho_e g l \frac{h^3}{6} + \rho_0 l \frac{h^2}{2} \right) \vec{y}$$

$$\text{D'où } \{T_{e \rightarrow b}\} = \begin{Bmatrix} X_{eb} & 0 \\ 0 & M_{eb} \\ 0 & 0 \end{Bmatrix}_{O,R}$$

$$\text{avec } \boxed{X_{eb} = \rho_2 g l \frac{h^2}{2} + P_0 l h}$$

$$X_{eb} = 1000 \cdot 10 \cdot 80 \cdot \frac{30^2}{2} + 10^5 \cdot 80 \cdot 30$$

$$\underline{X_{eb} = 600 \text{ MN}}$$

$$\boxed{M_{eb} = \rho_2 g l \frac{h^3}{6} + P_0 l \frac{h^2}{2}}$$

$$M_{eb} = 1000 \cdot 10 \cdot 80 \cdot \frac{30^3}{6} + 10^5 \cdot 80 \cdot \frac{30^2}{2}$$

$$\underline{M_{eb} = 18 \text{ GNm}}$$

④ Equilibre du lanage:  $\{T_{p \rightarrow b}\} + \{T_{e \rightarrow b}\} + \{T_{o \rightarrow b}\} = \{0\}$

$$\begin{Bmatrix} 0 & 0 \\ 0 & \frac{a}{3} Mg \\ -Mg & 0 \end{Bmatrix}_{O,R} + \begin{Bmatrix} X_{eb} & 0 \\ 0 & M_{eb} \\ 0 & 0 \end{Bmatrix}_{O,R} + \begin{Bmatrix} X_{ob} & 0 \\ 0 & M_{ob} \\ Z_{ob} & 0 \end{Bmatrix}_{O,R} = \begin{Bmatrix} 0 \\ 0 \\ 0 \end{Bmatrix}$$

$\perp$  pb plan  $(O, \vec{x}, \vec{y})$

$$\text{d'où } \boxed{X_{ob} = -X_{eb} = -600 \text{ MN}}$$

$$\boxed{Z_{ob} = Mg} = 62,4 \cdot 10^6 \cdot 10 = \underline{624 \text{ MN}}$$

$$\boxed{M_{ob} = -M_{eb} - \frac{a}{3} Mg} \quad \begin{aligned} M_{ob} &= -18 - \frac{20}{3} \cdot 62,4 \cdot 10^6 \cdot 10 \\ M_{ob} &= \underline{-226 \text{ GNm}} \end{aligned}$$

⑤ Conclusion: le valeurs des charges est

respecté car  $|X_{ob}| = 600 \text{ MN} \approx 600 \text{ MN}$

$|M_{ob}| = 226 \text{ GNm} < Mg = 624 \text{ MN}$