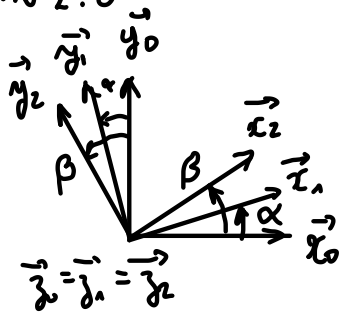


td CIN 2.0

7L55

①



②

$$\vec{\Omega}_{1/0} = \dot{\alpha} \vec{z}_0$$

$$\vec{\Omega}_{2/0} = \dot{\beta} \vec{z}_0$$

$$\vec{\Omega}_{3/0} = \vec{0}$$

Composition des vitesses : $\vec{\Omega}_{2/1} = \vec{\Omega}_{2/0} + \vec{\Omega}_{0/1}$

$$\vec{\Omega}_{2/1} = (\dot{\beta} - \dot{\alpha}) \vec{z}_0$$

③ $\vec{v}_{B,3/0} = \left(\frac{d \vec{OB}}{dt} \right)_0 = \left(\frac{d \lambda(t) \vec{y}_0}{dt} \right)_0$

$$\vec{v}_{B,3/0} = \dot{\lambda}(t) \vec{y}_0 \quad \text{car} \left(\frac{d \vec{y}_0}{dt} \right)_0 = \vec{0}$$

④ $\vec{v}_{A,1/0} = \left(\frac{d \vec{OA}}{dt} \right)_0 = \left(\frac{d e \vec{y}_1}{dt} \right)_0 = e \left(\frac{d \vec{y}_1}{dt} \right)_0$
 car e : constant

Bour $\left(\frac{d \vec{y}_1}{dt} \right)_0 = \vec{\Omega}_{1/0} \wedge \vec{y}_1 = \dot{\alpha} \vec{z}_0 \wedge \vec{y}_1$
 $\left(\frac{d \vec{y}_1}{dt} \right)_0 = -\dot{\alpha} \vec{x}_1$
 ↑ ou \vec{z}_1

$$\vec{v}_{A,1/0} = -e \dot{\alpha} \vec{x}_1$$

8h06

⑤

$$v_{A,1/0} = e \cdot |\dot{\alpha}| = e \frac{2\pi N_{110}}{60}$$

$$v_{A,1/0} = e \frac{\pi N_{110}}{30}$$

$$= 0,041 \cdot \frac{\pi \cdot 2000}{30}$$

$$v_{A,1/0} = 8,58 \text{ m} \cdot \text{s}^{-1}$$

1,7 cm

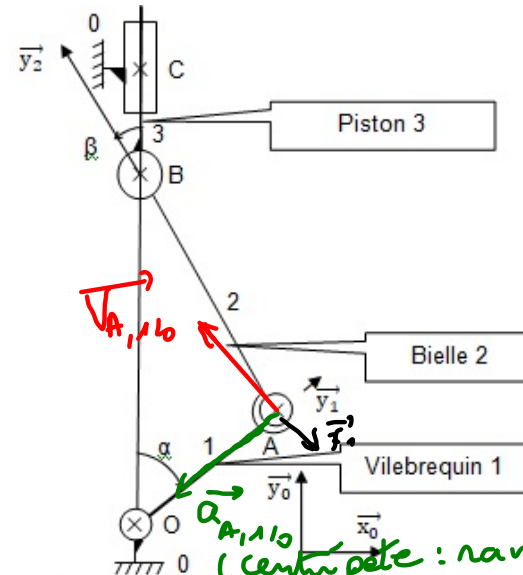


Figure 1 : Cinématique du moteur thermique.

(centripète : ramène la vitesse vers l'intérieure)
 $(u \cdot v)' = u' \cdot v + u \cdot v'$

⑥

$$\vec{a}_{A,1/0} = \left(\frac{d \vec{v}_{A,1/0}}{dt} \right)_0 = \left(\frac{d -e \dot{\alpha} \vec{x}_1}{dt} \right)_0$$

$$\vec{a}_{A,1/0} = \underbrace{-e \ddot{\alpha} \vec{x}_1}_{u'} \underbrace{-}_{v'} \underbrace{-e \dot{\alpha} \left(\frac{d \vec{x}_1}{dt} \right)_0}_{u'}$$

Bour $\left(\frac{d \vec{x}_1}{dt} \right)_0 = \vec{\Omega}_{1/0} \wedge \vec{x}_1 = \dot{\alpha} \vec{z}_0 \wedge \vec{x}_1$
 $\left(\frac{d \vec{x}_1}{dt} \right)_0 = \dot{\alpha} \vec{y}_1$

$$\vec{a}_{A,1/0} = -e \ddot{\alpha} \vec{x}_1 - e \dot{\alpha}^2 \vec{y}_1$$

si $\dot{\alpha} = N_{110} \cdot \frac{\pi}{30}$ alors $\ddot{\alpha} = 0$

$$a_{A,1/0} = e \left(\frac{N_{110} \pi}{30} \right)^2$$

$a_{A,1/0} = 1800 \text{ m} \cdot \text{s}^{-2}$ (1,8 cm)

8h18

⑦ Varignon : $\vec{V}_{A,1/0} = \vec{V}_{O,1/0} + \vec{AO} \wedge \vec{\Omega}_{1/0}$ 9236
 $= \vec{0} - e \vec{y}_1 \wedge \dot{\alpha} \vec{z}_1$
 $\vec{V}_{A,1/0} = -e \dot{\alpha} \vec{x}_1$

⑧ Composition des vitesses en A :
 $\vec{V}_{A,2/0} = \vec{V}_{A,2/1} + \vec{V}_{A,1/0}$
 $= \vec{0}$ car pivot en A entre 1 et 2
 Finalement $\vec{V}_{A,2/0} = -e \dot{\alpha} \vec{x}_1$

⑨ Varignon : $\vec{V}_{B,2/0} = \vec{V}_{A,2/0} + \vec{BA} \wedge \vec{\Omega}_{2/0}$
 $= -e \dot{\alpha} \vec{x}_1 + -L \vec{y}_2 \wedge \dot{\beta} \vec{z}_2$
 $\vec{V}_{B,2/0} = -e \dot{\alpha} \vec{x}_1 - L \dot{\beta} \vec{x}_2$

⑩ Composition des vitesses :
 $\vec{V}_{B,3/0} = \vec{V}_{B,3/2} + \vec{V}_{B,2/0}$
 \hookrightarrow car B : centre de la pivot entre 3 et 2
 $\vec{V}_{B,3/0} = -e \dot{\alpha} \vec{x}_1 - L \dot{\beta} \vec{x}_2$

⑪ Projection sur \vec{y}_0
 $\dot{\lambda}(t) = -e \dot{\alpha} \vec{x}_1 \cdot \vec{y}_0 - L \dot{\beta} \vec{x}_2 \cdot \vec{y}_0$
 $\dot{\lambda}(t) = -e \dot{\alpha} \sin \alpha - L \dot{\beta} \sin \beta$
 $\dot{\lambda}(t) = -e \dot{\alpha} \sin \alpha - L \dot{\beta} \sin \beta$

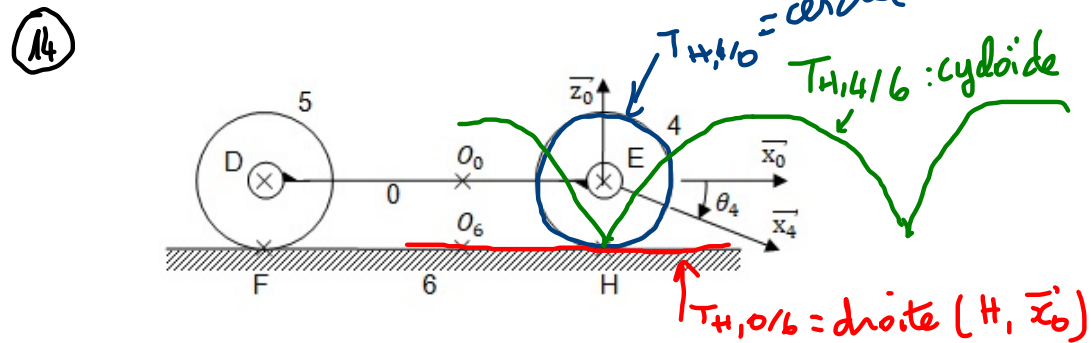
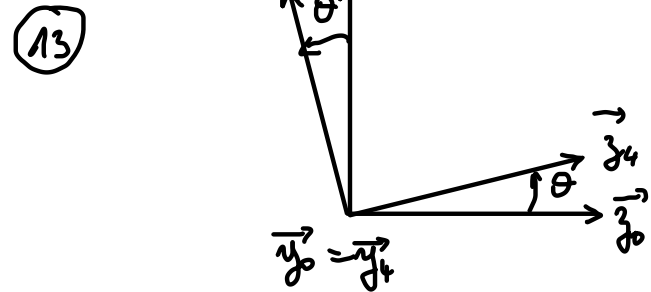
Projection sur \vec{x}_0 : $0 = -e \dot{\alpha} \cos \alpha - L \dot{\beta} \cos \beta$
 $\dot{\beta} = -\frac{e}{L} \frac{\cos \alpha}{\cos \beta} \dot{\alpha}$ si $\beta = \frac{\pi}{2} [\pi]$ 9250

$\dot{\lambda}(t) = -e \dot{\alpha} \sin \alpha + e \frac{\cos \alpha}{\cos \beta} \dot{\alpha} \sin \beta$

$\dot{\lambda}(t) = e \dot{\alpha} (\cos \alpha \tan \beta - \sin \alpha)$

⑫ $|\dot{\lambda}_{max}| = 12 \text{ m} \cdot \text{s}^{-1} < 30 \text{ m} \cdot \text{s}^{-1}$
 Les segments supportent largement ce critère, ce qui est normal car le moteur peut tourner plus vite que sa vitesse nominale.

9200
19204



15) Roulement sans glissement en H entre 4 et 6 :

$$\boxed{\vec{V}_{H,4/6} = \vec{0}}$$

16) Composition des vitesses :

$$\vec{V}_{H,4/0} + \vec{V}_{H,0/6} = \vec{0}$$

soit $\boxed{\vec{V}_{H,4/6} = -\vec{V}_{H,0/6}}$

17) Varignon : $\vec{V}_{H,4/0} = \underbrace{\vec{V}_{E,4/0}}_{=\vec{0}} + \vec{HE} \wedge \vec{\Omega}_{4/0}$
= 0 car E centre de la pivot entre 4 et 0.

$$\vec{V}_{H,4/0} = R \vec{z}_0 \wedge \dot{\theta}_4 \vec{y}_0$$

$$\boxed{\vec{V}_{H,4/0} = -R \dot{\theta}_4 \vec{x}_0}$$

Varignon : $\vec{V}_{H,0/6} = \underbrace{\vec{V}_{E,0/6}}_{=\left(\frac{d\vec{oe}}{dt}\right)_0} + \vec{HE} \wedge \underbrace{\vec{\Omega}_{0/6}}_{=\vec{0} \text{ translation.}}$

$$\boxed{\vec{V}_{H,0/6} = \dot{x} \vec{x}_0}$$

18) Par identification des 2 expressions :

$$\dot{x} = R \dot{\theta}_4 \quad \text{donc} \quad \boxed{V = R \frac{\pi N_{4/0}}{30}}$$

19) en m.s⁻¹ :

$$\boxed{V = R \frac{\pi N_{4/0}}{30 R_s}}$$

$$V = 0,406 \cdot \frac{\pi \cdot 2000}{30 \cdot 15,7}$$

$$V = 5,55 \text{ m.s}^{-1} \quad (20 \text{ km.h}^{-1})$$

en s^e :

$$\boxed{V = R \frac{\pi N_{4/0}}{30 R_s}}$$

$$V = 0,406 \cdot \frac{\pi \cdot 2000}{30 \cdot 3,06}$$

$$V = 27,8 \text{ m.s}^{-1} \quad (100 \text{ km.h}^{-1})$$

19h35